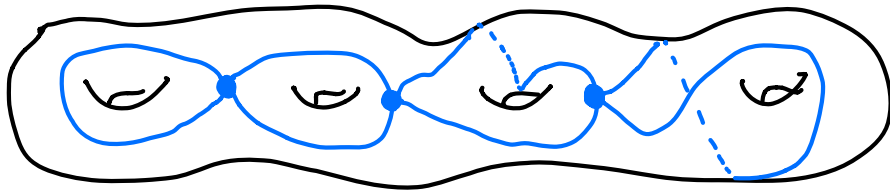


String nets and oriented 3-dimensional TQFTS

Part 1

Bruce Bartlett (Stellenbosch University)



Algebra group research seminar, University of Hamburg, 12 May 2020

Opening words

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- It's a bit more precise, and "mathematics-sounding".
- We can reserve the word "TQFT" for what it always referred to originally - a QFT with a topological action. So, eg. "The Chern-Simons TQFT gives rise to a bordism representation."

1. Introduction

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Asymptotic expansion conjecture The quantum Chern-Simons invariant Z_h of closed oriented 3-manifolds satisfies:

$$Z_h(M) \sim \frac{1}{2} e^{-\frac{3\pi i}{4}} \sum_{A \in \mathcal{M}_M^{\circ}} e^{2\pi i S_M(A) \cdot (h+2)} e^{\frac{-2\pi i I_A}{4}} \sqrt{\tau_M(A)}$$

Defined using quantum groups ...
or skein theory.

Asymptotic expansion conjecture

closed oriented 3-manifolds

$$Z_h(M)$$

$$\sim \frac{1}{2} e^{-\frac{3\pi i}{4}}$$

$$\sum_{A \in \mathcal{M}_M^0}$$

$$e^{2\pi i S_M(A) \cdot (h+2)}$$

$$e^{\frac{-2\pi i I_A}{4}}$$

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The quantum Chern-Simons invariant Z_h of
satisfies:

a sum over equivalence classes of
irreducible flat $SU(2)$ connections
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Asymptotic expansion conjecture
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The classical Chern-Simons invariant of A :

$$S_M(A) = \frac{1}{8\pi^2} \int_M \text{Tr}(A \wedge dA + \frac{2}{3} A \wedge A \wedge A)$$

Asymptotic expansion conjecture

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The interesting thing about the Atiyah-Patodi-Singer spectral flow $I_A(M)$ is ^{often} not so much the quantum invariant itself, but rather the fact that these invariants lead to interesting equations between these invariants. For example,

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The interesting thing about ^{often} the Franz-Reidemeister torsion is not so much the quantum invariant itself, but rather the fact that these invariants can be computed in different ways, leading to interesting equations between these invariants. For example,

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There are two standard ways of building a 3-dimensional oriented bordism representations from categorical data.

① Given a spherical fusion category \mathcal{C} , we get a "fully extended" bordism representation

$$\mathcal{Z}_{\mathcal{C}}^{\text{TVBW}} : \mathcal{Z}\text{Cob}_3^{\text{or}} \longrightarrow \mathcal{Z}\text{Vect}$$

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Uses surgery on knots, or the BHMV skein theory formalism.

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Given a spherical fusion category \mathcal{C} , we have

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→ used the computation of the coend of $\mathcal{Z}(\mathcal{C})$ via Hopf monads

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- Formulated TVBW as a "3-2-1" theory (their formalism did not use the language of higher categories)
- Related TVBW to RT on these basic building blocks.

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Given a spherical fusion category \mathcal{C} , he wrote down a generators-
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$$\sum_{123}^{\text{string nets}} : \text{Bord}_{123} \longrightarrow 2\text{Vect}$$

This refers to the finite presentation of the oriented 1-2-3 bordism bicategory found in:

B, Douglas, Schommer-Pries, Vicary. Extended 3-dimensional bordism as the theory of modular objects

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The graphical calculus technique of using a spherical fusion category to naturally associate vector spaces to surfaces. Came from physics (Levin-Wen), and formalized mathematically by Kirillov.

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This means a symmetric monoidal equivalence between 2-functors

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$$\mathbb{Z}^{\text{String nets}}_{123} \xrightarrow{\cong} \mathbb{Z}^{\text{TVBW}}_{123} : \text{Bord}_{123} \longrightarrow 2\text{Vect}$$

This refers to a bicategorical formulation of TVBW, in the language of generators-and-relations.

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This refers to a bicategorical formulation of TVBW, in the language of generators-and-relations. It's closely related to, but necessarily different, to the "3-2-1 theory" of Balsam-Kirillov.

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In these talks, I want to explain this idea of "string nets" and how it can be used to formulate both TVBW theory (based on a spherical category \mathcal{C}) and RT theory (based on a modular category \mathcal{D}) in an entirely graphical way.

2. String nets for spherical fusion categories

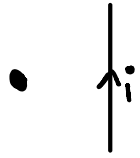
A fusion category is a \mathbb{C} -linear semisimple category, with finitely simple objects, equipped with the structure of a rigid monoidal category. We also demand that the tensor unit $\mathbb{1}$ is simple.

This is a finite, explicit, set of data. In graphical terms:

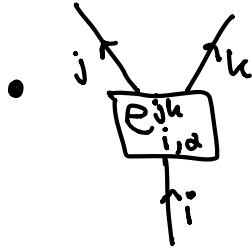
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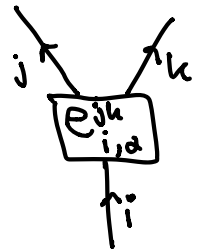
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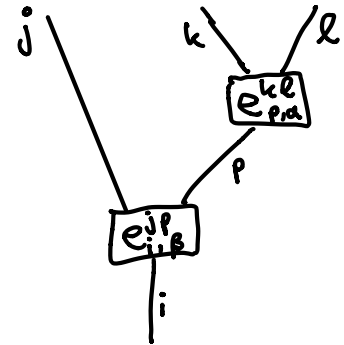
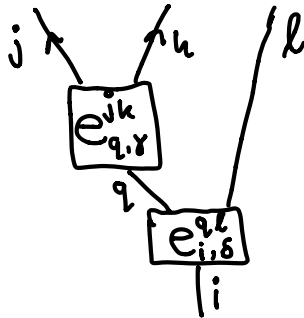


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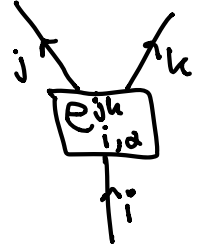
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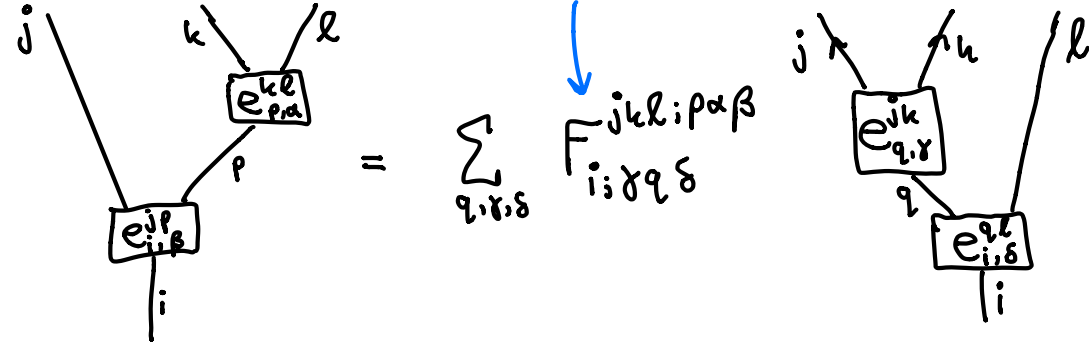
•  basis for $\text{Hom}(X_i, X_j \otimes X_k)$

•  = $\sum_{q,\gamma,\delta} F_{i;\gamma q \delta}^{jkl;p\alpha\beta}$ 

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-  simple objects $X_i, i=1 \dots n$

-  basis for $\text{Hom}(X_i, X_j \otimes X_k)$
must satisfy pentagon + rigidity

- 

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As I understand it, there are the simple objects $\mathbb{1} = X_1, \dots, X_n$, but now also their projective covers $P(X_i)$, and the action of the X_i on the $P(X_j)$ by tensoring (Cartan matrix?)

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$$X^* \cong {}^*X.$$

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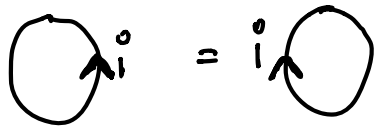
This amounts to a set of nonzero scalars $\{p_i\}_{i \in I}$ satisfying an equation.

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A pivotal structure is spherical if left and right dimensions agree:



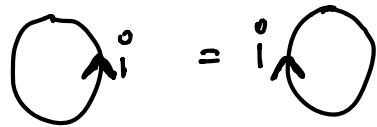
The diagram shows two circles representing objects in a fusion category. The left circle has an arrow labeled i pointing into it from the bottom. The right circle has an arrow labeled i pointing out of it from the bottom. The two circles are separated by an equals sign, indicating that the left and right dimensions are equal.

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The diagram shows two circles representing objects in a fusion category. The left circle has a small dot on its right side with an arrow pointing into the circle, labeled with the index i . The right circle has a small dot on its left side with an arrow pointing into the circle, also labeled with the index i . An equals sign is placed between the two circles, indicating that these two configurations are equivalent.

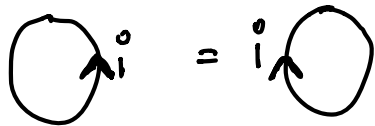
This means that a C -labelled string diagram on the sphere can be unambiguously evaluated.

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A pivotal structure is spherical if left and right dimensions agree:


$$\bigcirc \uparrow^i = \downarrow^i \bigcirc$$

This means that a C -labelled string diagram on the sphere can be unambiguously evaluated. A spherical fusion category is a fusion category equipped with a spherical structure.

Example 1 $\text{Vect}[G]$, G a finite group.

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- Simple objects \uparrow $a \in G$

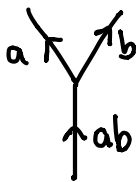
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- Simple objects



$a \in G$

- Fusion rules



$a, b \in G$

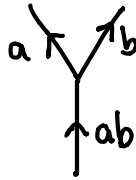
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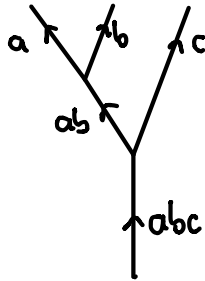
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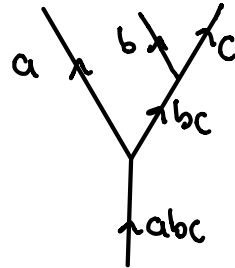


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- Associators



=

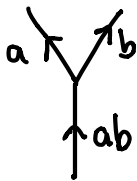


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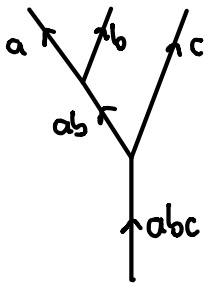
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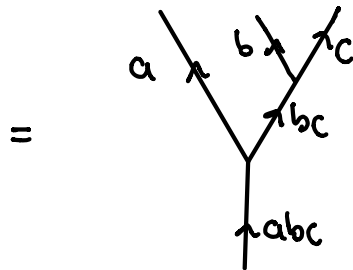
$a \in G$

a spherical structure on $\text{Vect}[G]$

=
a group homomorphism

$$G \rightarrow \mathbb{Z}/2\mathbb{Z}$$

$a, b \in G$



Example 1 $\text{Vect}^{\omega}[G]$, G a finite group.

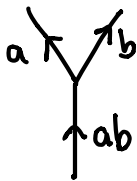
$\omega \in Z^3(G, U(1))$

- Simple objects



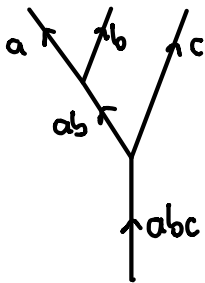
$a \in G$

- Fusion rules

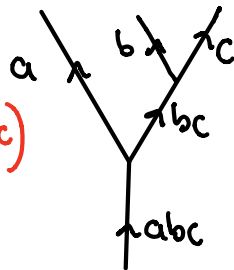


$a, b \in G$

- Associators



$= \omega(a, b, c)$



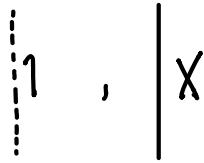
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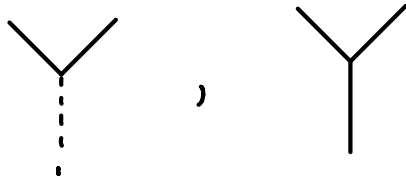
- simple objects 1 , X

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- simple objects

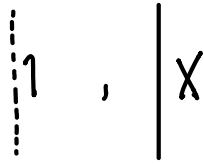


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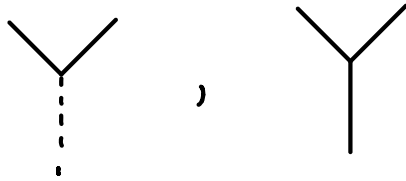


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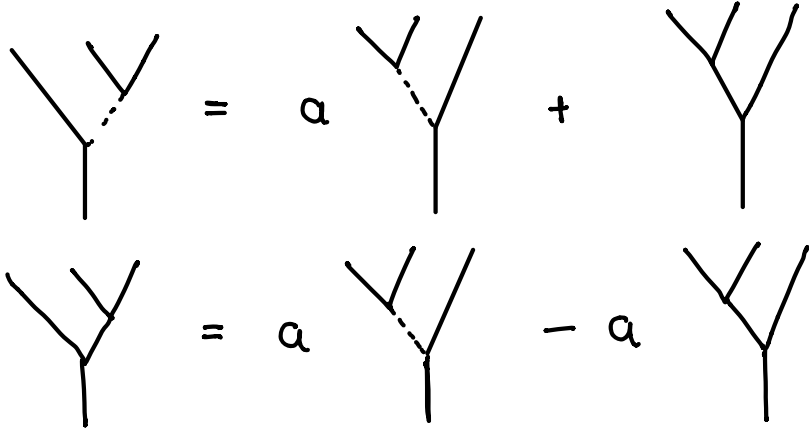
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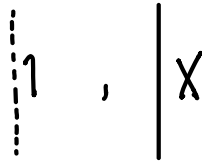
- associators



$$a = -\frac{1}{2}(1 + \sqrt{5})$$

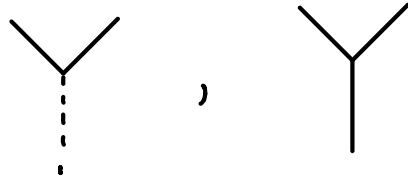
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- simple objects



$$|| = a \begin{array}{c} \cup \\ \vdots \\ \cap \end{array} + \begin{array}{c} \diagup \\ \diagdown \end{array}$$

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Definition (Kitaev 2003, Levin-Wen 2005, Kirillov 2011) The string-net space of Σ is

$$S_{\mathcal{C}}(\Sigma) := \mathbb{C} \left[\begin{array}{c} \text{isotopy classes of } \mathcal{C}\text{-labelled graphs} \\ \text{on } \Sigma \end{array} \right] / \text{local relations}$$

Let \mathcal{C} be a spherical fusion category and Σ an oriented surface, which may have boundary.

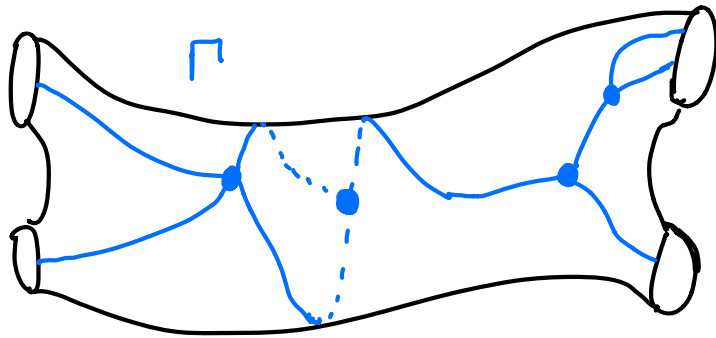
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(See also Gooson, Oriented 123-TQFTS via String-Nets and State-Sums, PhD thesis, 2018)

Let Γ be a finite unoriented graph smoothly embedded in Σ . If Σ has a boundary, we require Γ to have univalent vertices located on $\partial\Sigma$.

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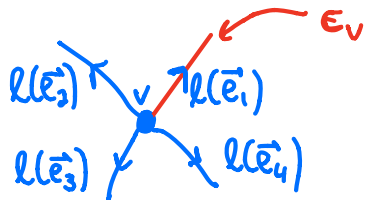
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outgoing orientation, in counterclockwise order (using orientation of Σ !)
Starting at e_v .

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The boundary-value of a C -labelled graph is

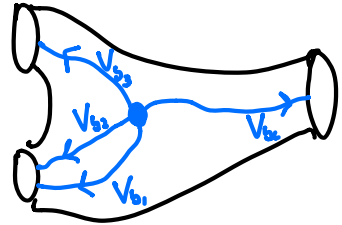
$$\underline{V} = (B, \{V_b\})$$

where $B = \{b_1, \dots, b_n\} \subset \partial\Sigma$ are the positions of the univalent vertices on $\partial\Sigma$, and the objects $V_b \in C$ are the labels of the outgoing (i.e. "leaving Σ ") oriented edges.

The boundary-value of a \mathbb{C} -labelled graph is

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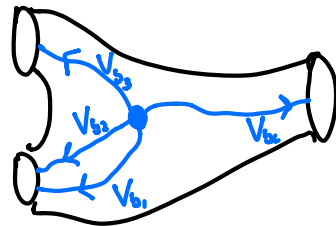


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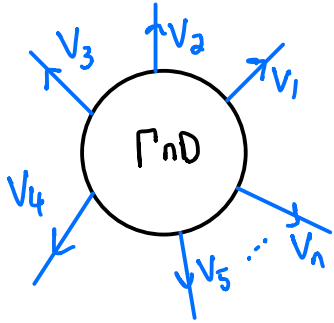
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We write $\text{Graph}(\Sigma, \underline{V})$ for the collection of all C -labelled graphs on Σ with boundary value \underline{V} .

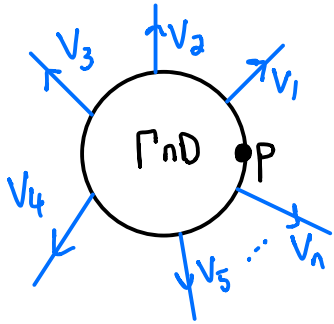


let Γ be a C -labelled graph inside an oriented surface Σ , and
let $D \subset \Sigma$ be an embedded disk, such that ∂D intersects the
edges of Γ transversally.

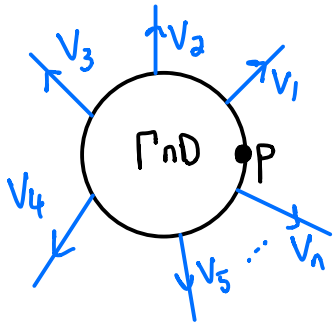
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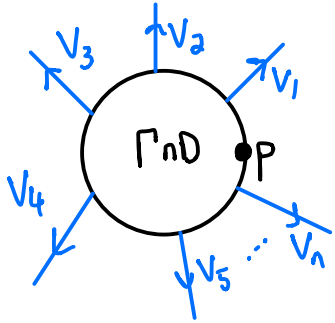
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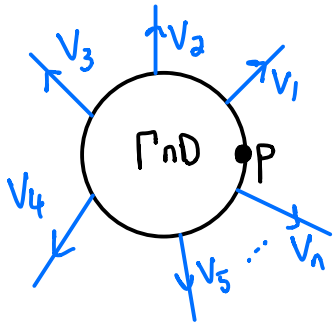


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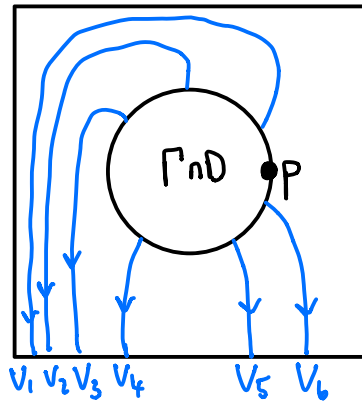


The evaluation of Γ in D is the resulting $\langle \Gamma \rangle_D \in \text{Hom}(1, V_1 \otimes \dots \otimes V_n)$.

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$\langle \Gamma \rangle =$



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(sorry!)

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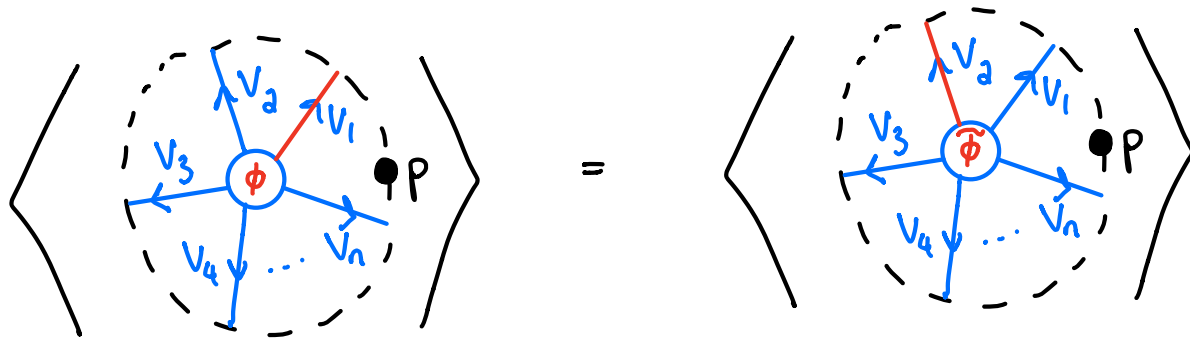
Properties

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- Rotating the choice of initial edge :

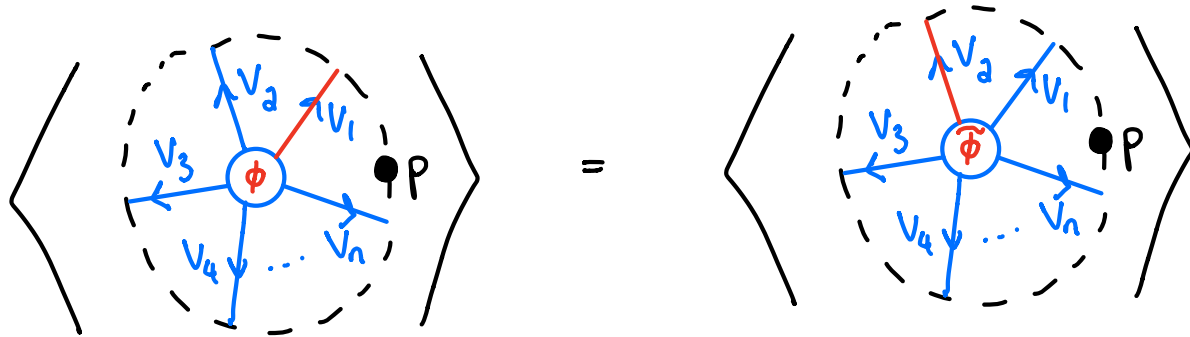
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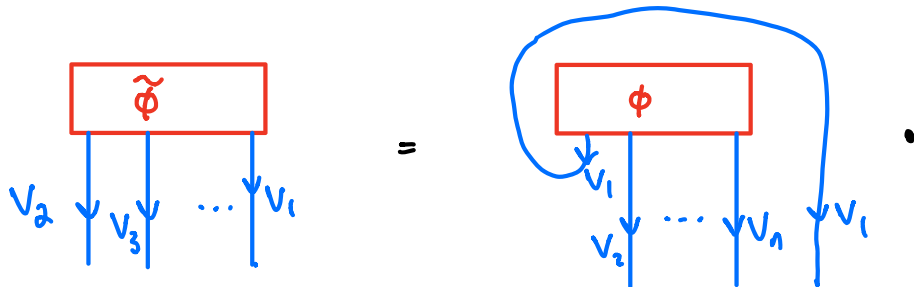


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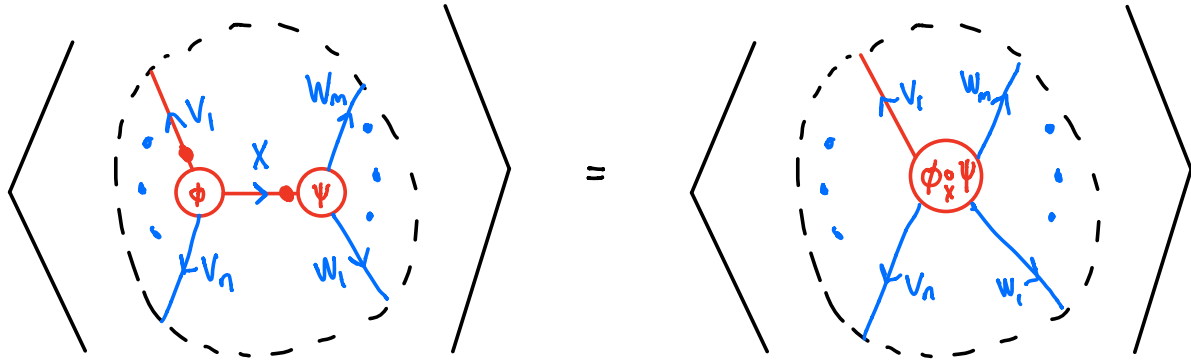


where

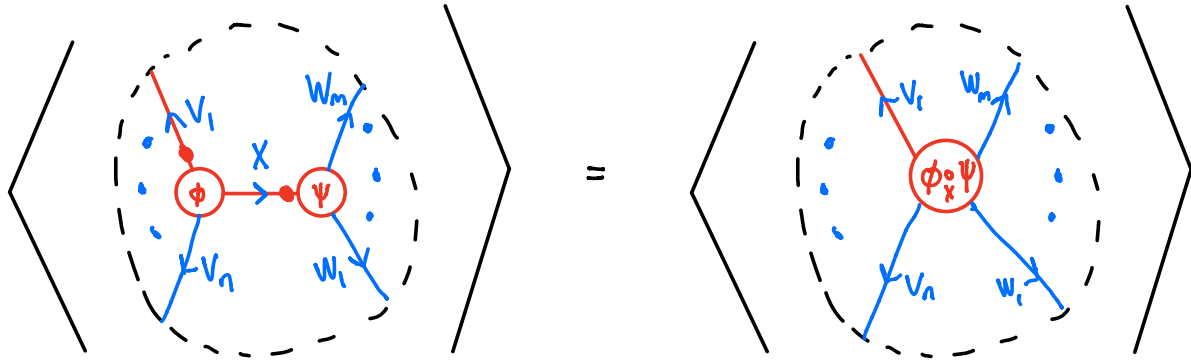


- Merging of vertices :

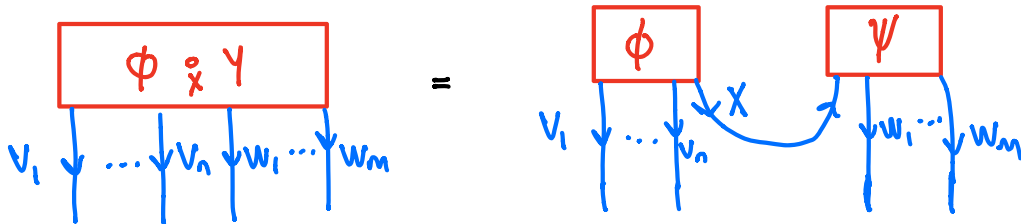
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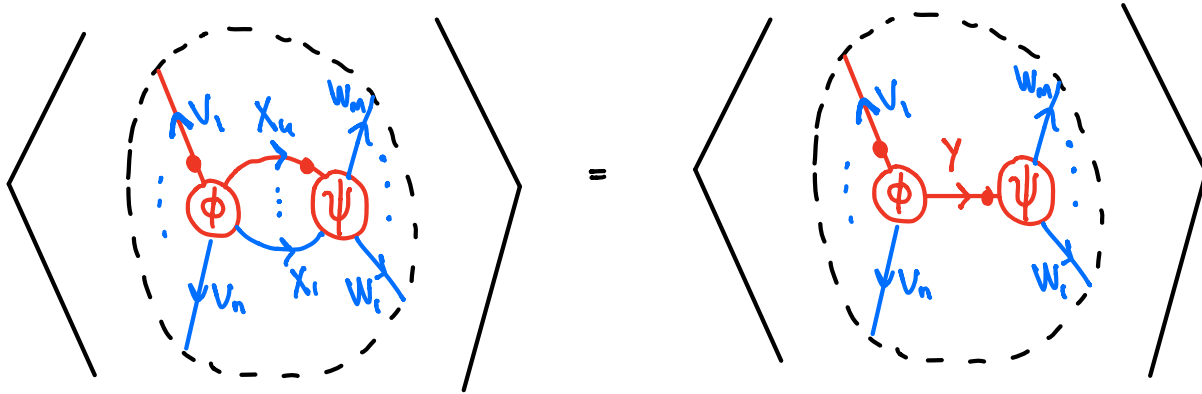


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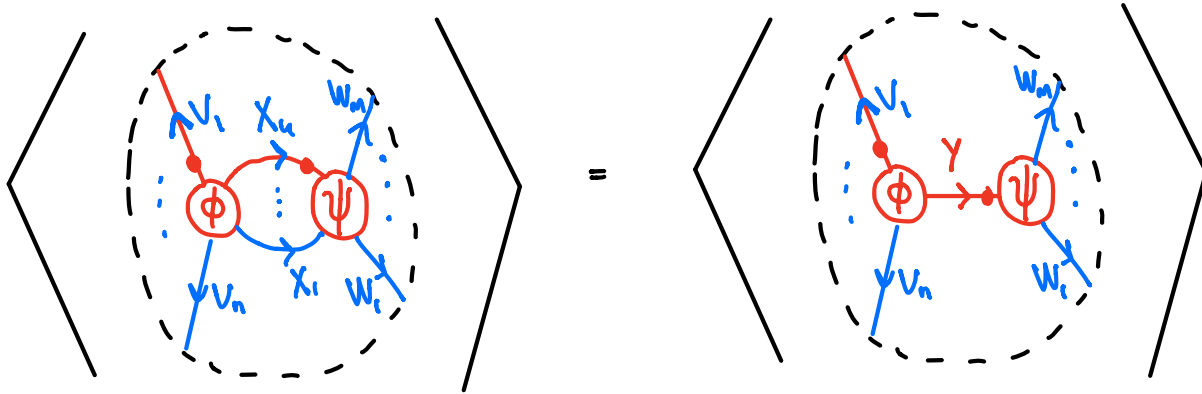
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the subspace formed by the union of all null combinations for all embedded disks

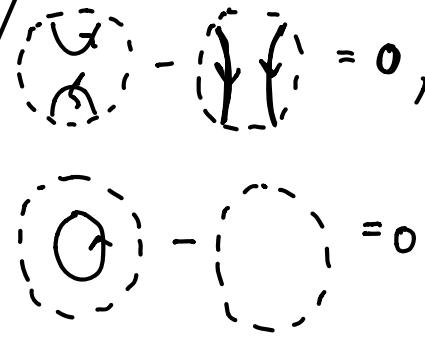
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The nice thing about this definition is that it is very natural, and is similar in spirit to standard algebraic topology constructions.

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Compare with eg.

$$H_1(\Sigma; \mathbb{Z}) = \mathbb{Z} \left[\begin{array}{l} \text{oriented} \\ \text{in } \Sigma \end{array} \text{ 1-manifolds} \right] /$$


The diagram illustrates two types of 1-manifolds in a surface Σ . The first row shows a circle with a counter-clockwise arrow (labeled 'G') and a pair of pants with two downward arrows, with an equals zero symbol. The second row shows a circle with a clockwise arrow (labeled 'G') and an empty circle, also with an equals zero symbol.

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Indeed, string nets is morally the same thing as factorization homology.

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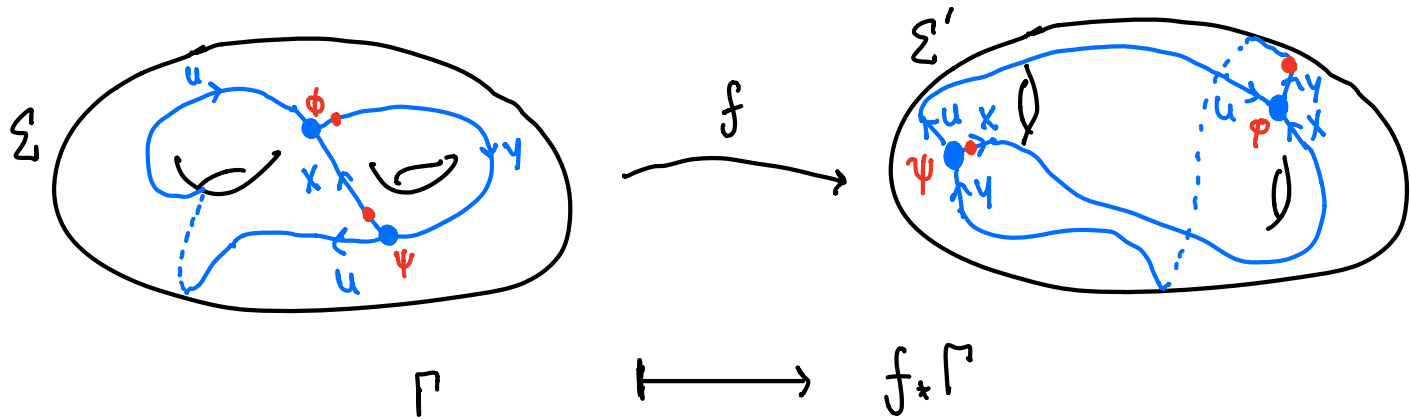
The diagram shows two rows of dashed circles representing 1-manifolds. The top row shows a circle with a counter-clockwise arrow minus a circle with two vertical arrows pointing downwards, equated to zero. The bottom row shows a circle with a counter-clockwise arrow minus an empty circle, also equated to zero.

The string-net spaces are monoidal with respect to disjoint union:

$$\mathcal{Z}^{\text{String}}(\Sigma_1 \sqcup \Sigma_2) \cong \mathcal{Z}^{\text{String}}(\Sigma_1) \otimes \mathcal{Z}^{\text{String}}(\Sigma_2)$$

But most importantly, string nets can be naturally pushed forward
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Example For the Yang-Hee category with simple objects

⋮
1

|
X

Example

For the Yang-Hee category with simple objects



(recall eg. $\left| \left| \right. = a \begin{array}{c} \cup \\ \cap \end{array} + \begin{array}{c} \vee \\ \wedge \end{array} , a = -\frac{1}{2}(1 + \sqrt{5}) \right)$

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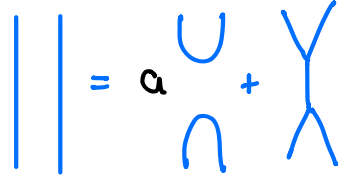


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X

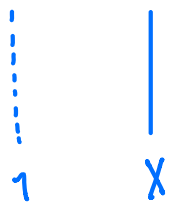
(recall
eg.



$$, a = -\frac{1}{2}(1 + \sqrt{5})$$

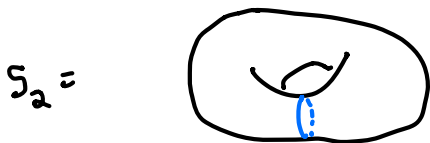
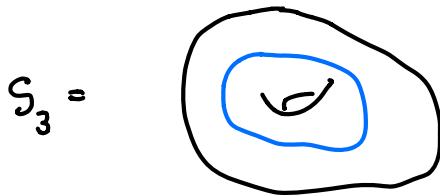
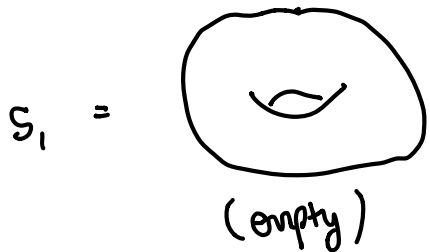
the following is a basis for $Z^{\text{string}}(\text{torus})$:

Example For the Yang-lee category with simple objects



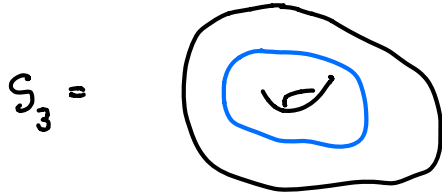
(recall eg. $|| = a \begin{array}{c} \cup \\ \cap \end{array} + \begin{array}{c} \diagup \\ \diagdown \end{array}$, $a = -\frac{1}{2}(1 + \sqrt{5})$)

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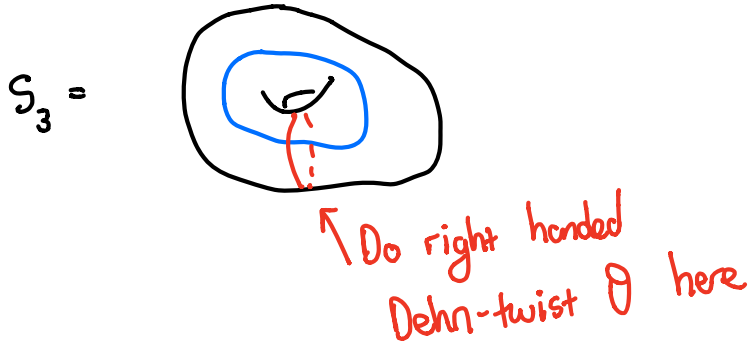


Let us compute the action of a right handed Dehn twist on S_3 ,
for example:

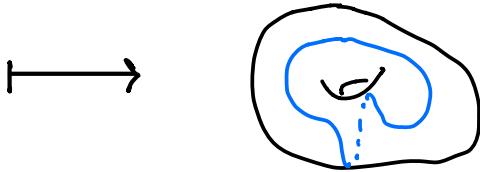
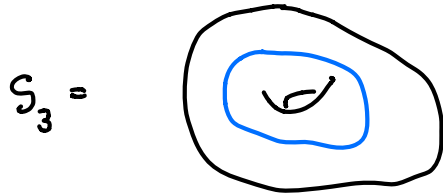
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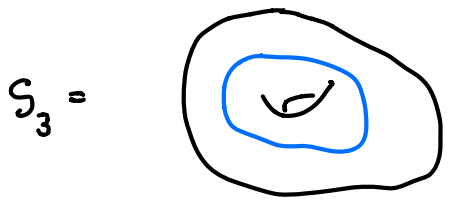
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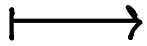
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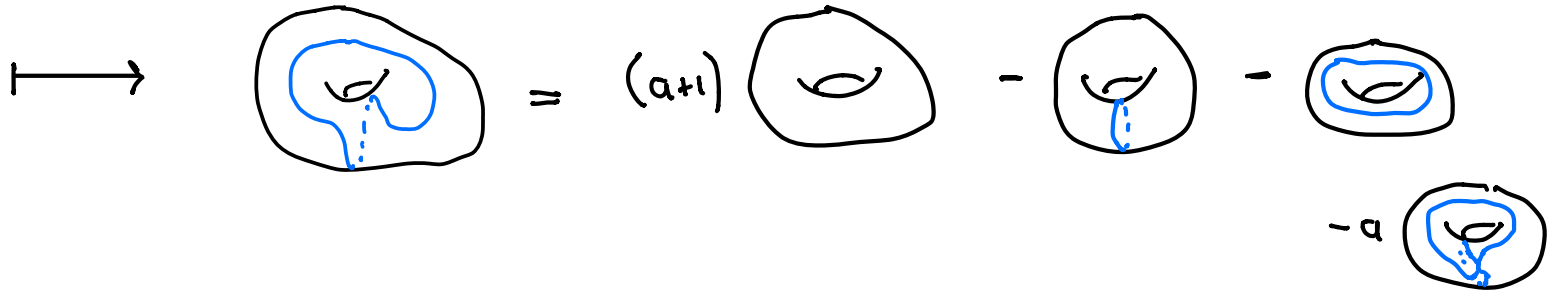
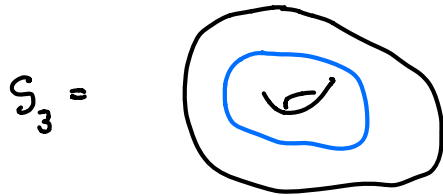


use local relations

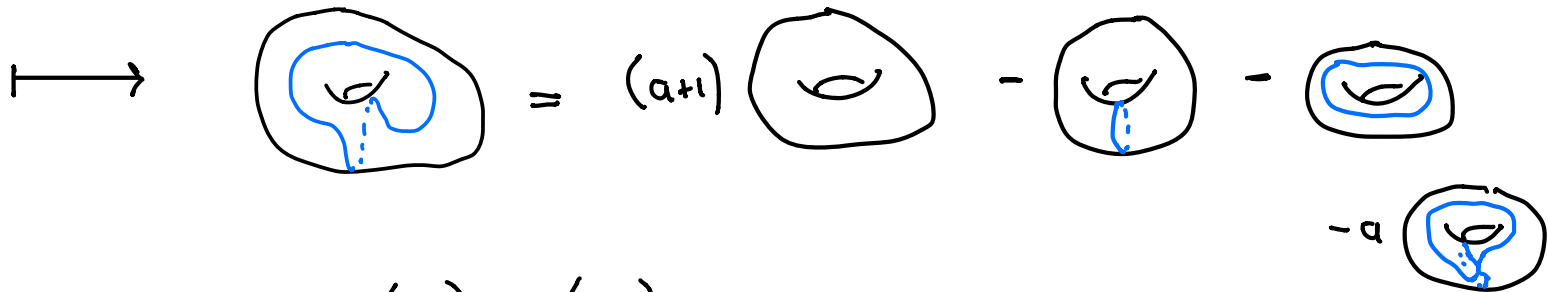


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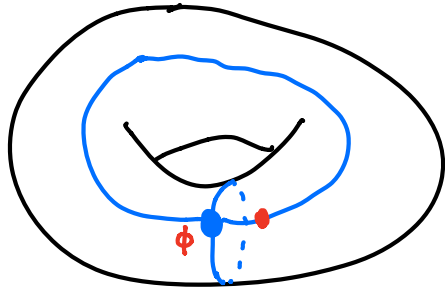
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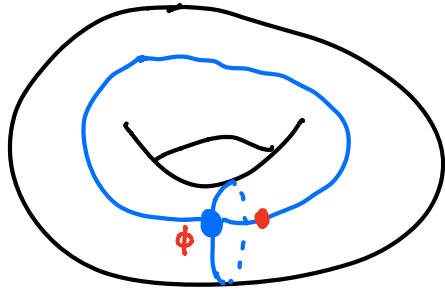
$$\text{So, } f_x(S_3) = (a+1)S_1 - S_2 - S_3 - aS_4.$$

The Yang-Hee category also shows why we need to keep track of the marked half-edges!

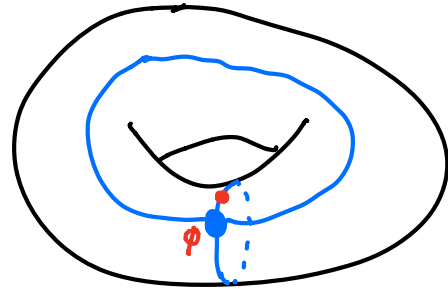
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S-move
→



The Yang-Hee category also shows why we need to keep track of the marked half-edges!

